

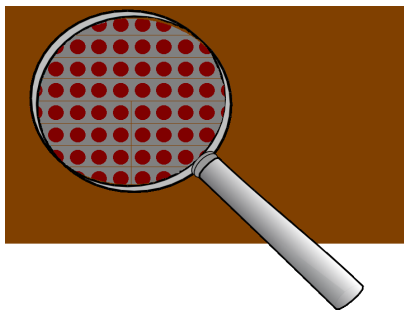
# A problem of optimal design of composites

Luis Silvestre

Courant Institute

Oct. 25th, 2007

# Composite materials



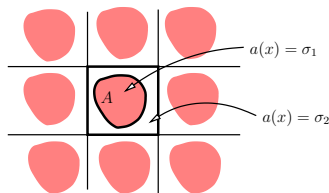
Composites are engineered materials made from two or more constituent materials with significantly different physical properties (For ex. Thermal conductivity).

The mixing of the materials is at a small scale, we compute the conductivity properties at a larger scale by a process called homogenization.

## Periodic composites

In a periodic two-component composite, the conductivity at each point is given by a periodic function  $a$  with the following form in the unit cube  $Q$ .

$$a(x) = \begin{cases} \sigma_1 & \text{if } x \in A \\ \sigma_2 & \text{if } x \in Q \setminus A \end{cases}$$



Where  $A$  is the part of the cube covered by the first constituent material.

# homogenization

If the function  $a$  is periodic in cubes of size  $\varepsilon$ , we have equations like

$$\operatorname{div}(a(x/\varepsilon)\nabla u^\varepsilon(x)) = f(x)$$

As  $\varepsilon \rightarrow 0$ , the solutions  $u^\varepsilon$  will converge to a solution  $u$  to the *homogenized* problem:

$$\operatorname{div}(A_{\text{eff}}\nabla u(x)) = f(x)$$

where the matrix  $A_{\text{eff}}$  depends on  $\sigma_1$ ,  $\sigma_2$  and the exact shape of the set  $A$ .

# Cell problem

## Formula to obtain $A_{\text{eff}}$

The matrix  $A_{\text{eff}}$  is a self-adjoint matrix such that

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

Note that  $\langle A_{\text{eff}} v, v \rangle$  is the energy of a function  $u(x) = x \cdot v + w(x)$  that is periodic perturbation of a plane and solves

$$\operatorname{div}(a(x)\nabla u) = 0 \quad \text{in } Q$$

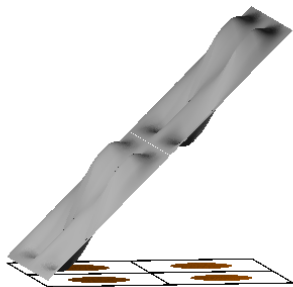
# Interpretation of the cell problem



The function  $u = x \cdot v + w$  is a periodic perturbation of a plane that solves  $\operatorname{div}(a(x)\nabla u) = 0$  in  $Q$ .

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

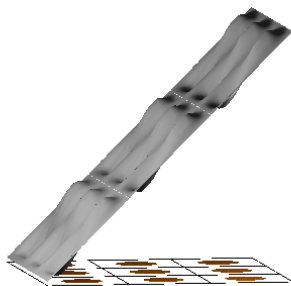
# Interpretation of the cell problem



The function  $u = x \cdot v + w$  is a periodic perturbation of a plane that solves  $\operatorname{div}(a(x)\nabla u) = 0$  in  $Q$ .

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem

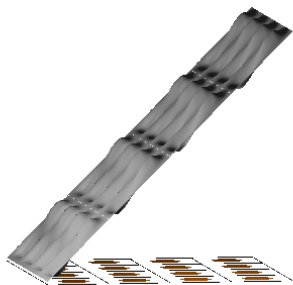


The function  $u = x \cdot v + w$  is a periodic perturbation of a plane that solves  $\operatorname{div}(a(x)\nabla u) = 0$  in  $Q$ .

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$



# Interpretation of the cell problem



The function  $u = x \cdot v + w$  is a periodic perturbation of a plane that solves  $\operatorname{div}(a(x)\nabla u) = 0$  in  $Q$ .

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

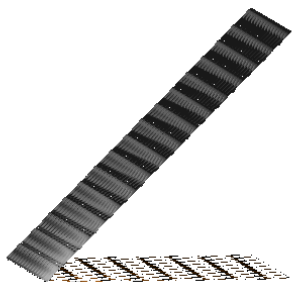
# Interpretation of the cell problem



The function  $u = x \cdot v + w$  is a periodic perturbation of a plane that solves  $\operatorname{div}(a(x)\nabla u) = 0$  in  $Q$ .

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

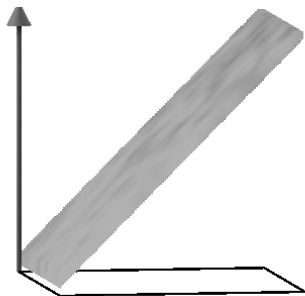
# Interpretation of the cell problem



In a coarser scale, the function  $u$  approximates a plane. Its energy is still  $\langle A_{\text{eff}} v, v \rangle$ .

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

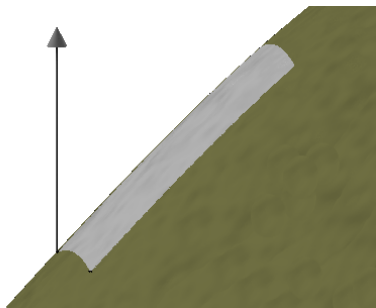
# Interpretation of the cell problem



In a coarser scale, the function  $u$  approximates a plane. Its energy is still  $\langle A_{\text{eff}} v, v \rangle$ .

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

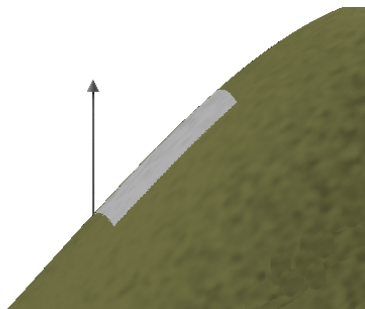
# Interpretation of the cell problem



In an even larger scale, it could be a piece of a smooth function.

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

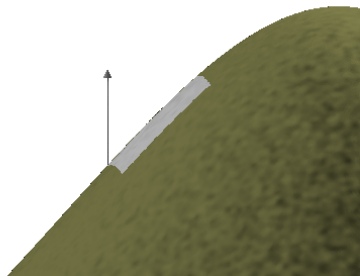
# Interpretation of the cell problem



In an even larger scale, it could be a piece of a smooth function.

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem



In an even larger scale, it could be a piece of a smooth function.

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem

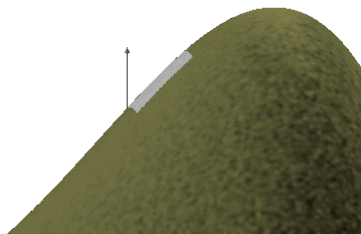


In an even larger scale, it could be a piece of a smooth function.

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$



# Interpretation of the cell problem



In an even larger scale, it could be a piece of a smooth function.

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

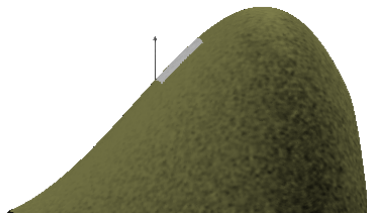
# Interpretation of the cell problem



In an even larger scale, it could be a piece of a smooth function.

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

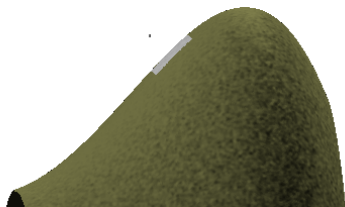
# Interpretation of the cell problem



In an even larger scale, it could be a piece of a smooth function.

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem



In an even larger scale, it could be a piece of a smooth function.

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem



In an even larger scale, it could be a piece of a smooth function.

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem



In an even larger scale, it could be a piece of a smooth function.

$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem

In an even larger scale, it could be a piece of a smooth function.



$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem

In an even larger scale, it could be a piece of a smooth function.



$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$



# Interpretation of the cell problem

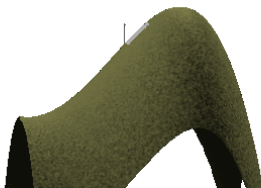
In an even larger scale, it could be a piece of a smooth function.



$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem

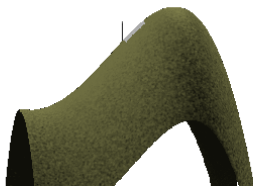
In an even larger scale, it could be a piece of a smooth function.



$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem

In an even larger scale, it could be a piece of a smooth function.



$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem

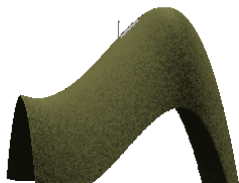
In an even larger scale, it could be a piece of a smooth function.



$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem

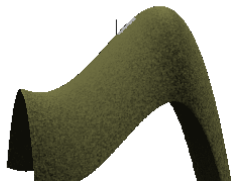
In an even larger scale, it could be a piece of a smooth function.



$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem

In an even larger scale, it could be a piece of a smooth function.



$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Interpretation of the cell problem

In an even larger scale, it could be a piece of a smooth function.



$$\langle A_{\text{eff}} v, v \rangle = \min_{w \in H_{\text{per}}^1(Q)} \int_Q a(x) |v + \nabla w|^2 dx.$$

# Effective conductivity.

In general  $A_{\text{eff}}$  is a selfadjoint  $n \times n$  matrix.

In case the set  $A$  (the part of the unit cube occupied by the first component) is cubically symmetric, then we know  $A_{\text{eff}}$  will be a scalar  $a_{\text{eff}}I$ .



## First Question of optimization.

### Question

Given  $\sigma_1 < \sigma_2$  and  $\mu > 0$ , what is the maximum value that  $a_{\text{eff}}$  can take for all cubically symmetric shapes  $A$  such that  $|A| = \mu$ ??

### Answer

The maximum conductivity is given by the Hashin-Shtrikman bound:

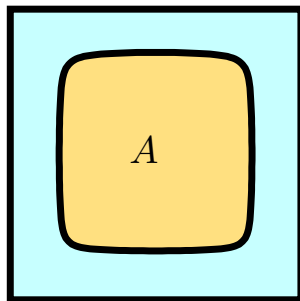
$$a_{\text{eff}} \leq \mu\sigma_1 + (1 - \mu)\sigma_2 - \frac{\mu(1 - \mu)(\sigma_2 - \sigma_1)^2}{(n\sigma_2 + (1 - \mu)(\sigma_1 - \sigma_2))}$$

Moreover, there is a unique connected shape  $A$  that realizes the bound and it is given by the contact set of an obstacle problem.

## General Vigdergauz structures

The unique connected shape  $A$  that achieves the Hashin-Shtrikman bound is the contact set of the following *obstacle* problem.

- $q$  is a  $Q$ -periodic function.
- $q \geq -|x|^2$  in  $Q$ .
- $\Delta q(x) = k$  for every  $x$  where  $q(x) > -|x|^2$ .
- $\Delta q(x) \leq k$  in  $Q$ .



## A more symmetric problem

Consider a composite where one constituent is a good thermal conductor (conductivity 1) but a bad electric conductor (conductivity  $\varepsilon$ ). The other has the exact opposite properties: thermal conductivity  $\varepsilon$  and electric conductivity 1.

Let  $a_{\text{eff}}$  and  $b_{\text{eff}}$  be the effective thermal and electric conductivities of the mix.

In a series of papers, Torquato, Hyun and Donev studied the problem of maximizing  $a_{\text{eff}} + b_{\text{eff}}$  from all cubically symmetric shapes  $A$  in 3D such that  $|A| = |Q|/2$ .

Not that if we exchange  $A$  with  $Q \setminus A$ , the quantity  $a_{\text{eff}} + b_{\text{eff}}$  does not change.

## Bergman's bounds

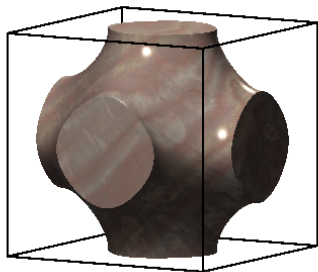
Using classical cross-property bounds due to Bergman (1978), we can obtain the following upper bound in 3D:

$$a_{\text{eff}} + b_{\text{eff}} \leq (1 + \varepsilon) - \frac{(1 - \varepsilon)^2}{3(1 + \varepsilon)}.$$

**Question:** Is the bound achievable?

**Pseudo-answer:** Numeric computations by Torquato, Hyun and Donev suggest it is.

## The expected optimal microstructure

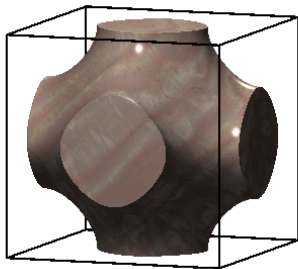


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

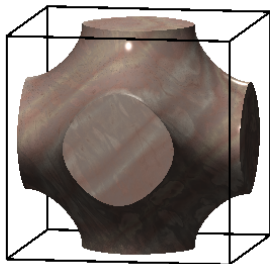


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

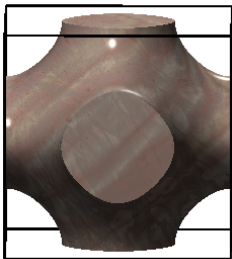


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure



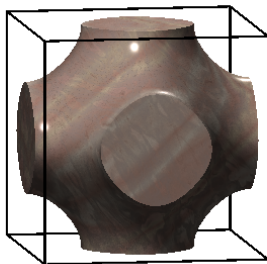
The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.



## The expected optimal microstructure

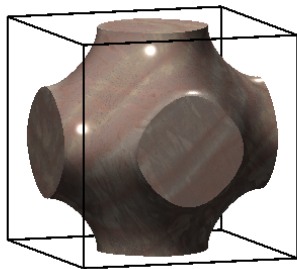


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

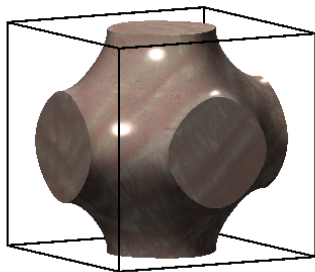


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

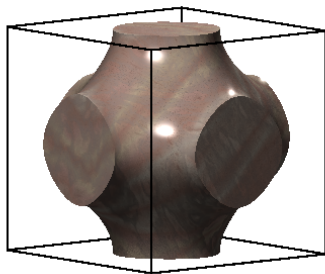


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

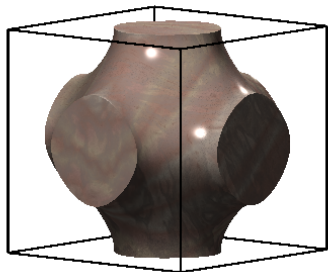


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

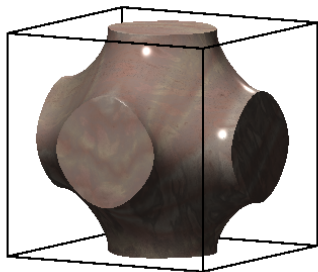


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

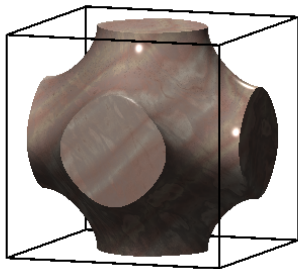


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

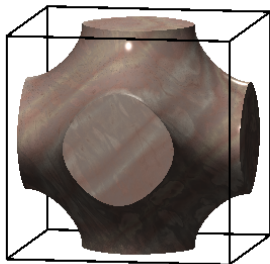


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure



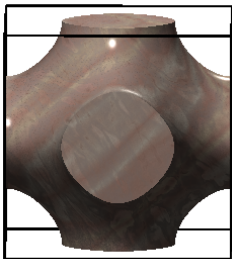
The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.



## The expected optimal microstructure

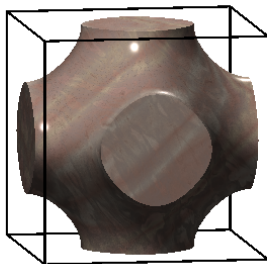


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

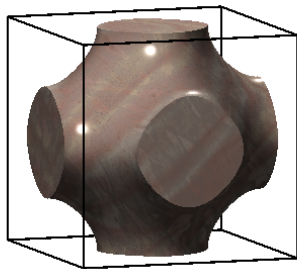


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

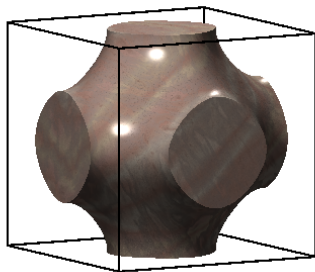


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

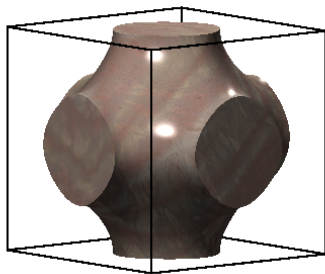


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

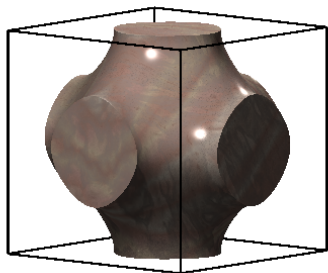


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

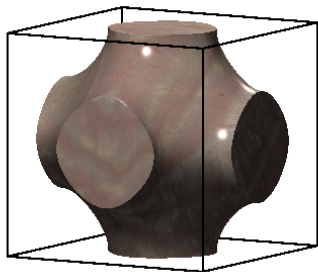


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

## The expected optimal microstructure

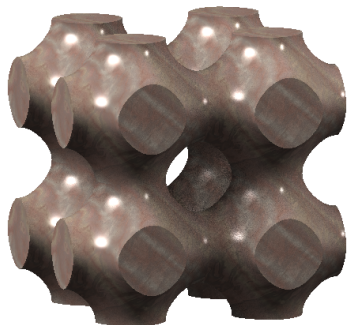


The expected shape of an optimal structure  $A$  would be triply connected.

Moreover  $Q \setminus A$  would be triply connected too.

Moreover  $A$  and  $Q \setminus A$  should be congruent sets due to the symmetry of the problem.

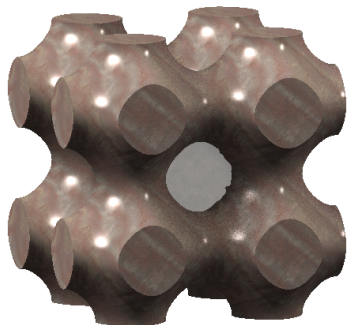
The set  $A$  and  $Q \setminus A$  are identical up to translation



$Q \setminus A$  is the same as  $A$  translated half diagonal of the unit cube.



The set  $A$  and  $Q \setminus A$  are identical up to translation



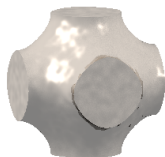
$Q \setminus A$  is the same as  $A$  translated half diagonal of the unit cube.

The set  $A$  and  $Q \setminus A$  are identical up to translation



$Q \setminus A$  is the same as  $A$  translated half diagonal of the unit cube.

The set  $A$  and  $Q \setminus A$  are identical up to translation



$Q \setminus A$  is the same as  $A$  translated half diagonal of the unit cube.

The set  $A$  and  $Q \setminus A$  are identical up to translation

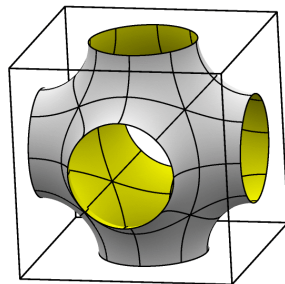


$Q \setminus A$  is the same as  $A$  translated half diagonal of the unit cube.

# Conjecture.

From the numeric computations it was natural to believe that  $\partial A$  was the Schwartz  $P$  surface.

The Schwartz  $P$  surface is a bicontinuous periodical minimal surface.



Picture of the Schwartz  $P$  surface from the website of Ken Brakke.

# Characterization of optimal structures

## Theorem

*Bergman's upper bound is achieved for a set  $A \subset Q$  if and only if the periodic solution to*

$$\Delta q = \begin{cases} 1 & \text{in } A \\ -1 & \text{in } Q \setminus A \end{cases}$$

*satisfies*

$$D^2 q(x) = \begin{cases} M(x) + \nu \otimes \nu & \text{on the } A \text{ side of } \partial A \\ M(x) - \nu \otimes \nu & \text{on the } Q \setminus A \text{ side of } \partial A \end{cases}$$

*for some matrix  $M$  such that  $M(x) \cdot \nu = 0$ .*

*Proof in the blackboard.*

# Counterproof of the conjecture

## Question

Can Bergman's upper bound be achieved if  $\partial A$  has mean curvature zero?

If that was the case, it can be shown that

- $q$  is constant ( $= 0$ ) on  $\partial A$ .
- $q_\nu$  is also constant on  $\partial A$ .

So, at the same time we would have that  $q^+$  and  $q^-$  solve the one phase problem, and  $q$  solves the two-phase membrane problem.

For a given set  $A$ , these conditions can be checked numerically in a very simple way. Indeed, they are **not** satisfied if  $\partial A$  is the Schwartz  $P$  surface.