

# Lower dimensional obstacle problems and the fractional Laplacian

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joint work with Luis Caffarelli and Sandro Salsa

## Classical Obstacle problem

Let us consider a surface given by the graph of a function  $u$ .



$u$  is a function solving  $\Delta u = 0$  for fixed boundary data. (we can think of an elastic membrane)

Let us now slide an obstacle from below. The surface must stay above it. For a given obstacle  $\varphi$ , we obtain a function  $u \geq \varphi$ , that will try to be as harmonic as possible.

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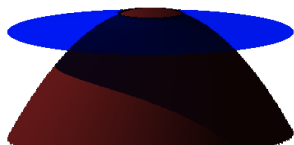
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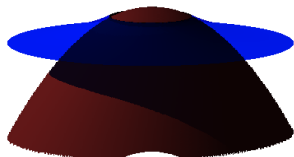
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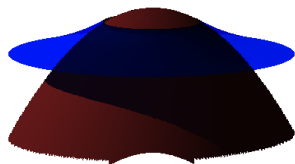
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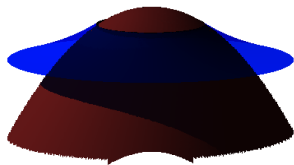
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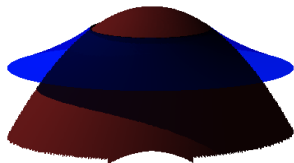
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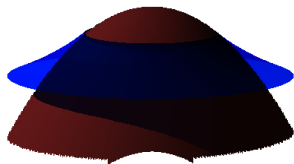


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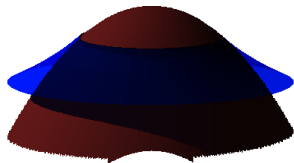


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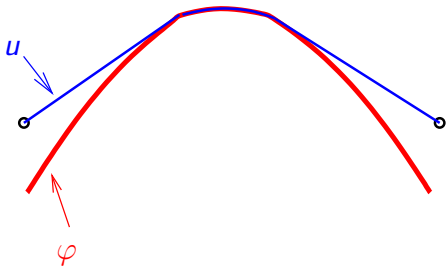


# Classical Obstacle problem

$\Delta u = 0$  where  $u > \varphi$ , since there  $u$  is free to move

$\Delta u \leq 0$  everywhere, since the surface pushes down

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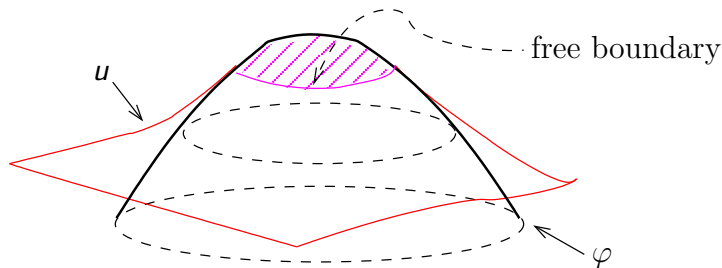


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## Regularity results

The regularity results for the classical obstacle problems are

- The function  $u \in C^{1,1}$  (Frehse 1972).
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## Stochastic approach

$$u(x) = \sup_{\tau} E(\varphi(B_{\tau}^x))$$

where  $B_t^x$  is Brownian motion starting at  $x$  and  $\tau$  is any stopping time.

Then

$$-\Delta u = 0$$

$$-\Delta u \geq 0$$

$$u \geq \varphi$$

where  $u > \varphi$  (at the points of no stop)

everywhere in  $\mathbb{R}^n$

A model like this is used in financial mathematics for pricing American options

## Jump processes

We now consider

$$u(x) = \sup_{\tau} E(\varphi(X_{\tau}^x))$$

where  $X_t^x$  is a purely jump process starting at  $x$  and  $\tau$  is any stopping time.

Then

$$\begin{aligned} Lu &= 0 && \text{where } u > \varphi \text{ (at the points of no stop)} \\ Lu &\geq 0 && \text{everywhere in } \mathbb{R}^n \\ u &\geq \varphi \end{aligned}$$

where the operator  $L$  has the integro-differential form

$$Lu(x) = \text{PV} \int_{\mathbb{R}^n} (u(x) - u(x+y))K(y) dy$$

for some positive kernel  $K$ .

# Fractional laplacian

Natural example:

$$Lu(x) = \text{PV} \int_{\mathbb{R}^n} \frac{u(x) - u(x+y)}{|y|^{n+2s}} dy = C(-\Delta)^s u(x)$$

Corresponds to  $\alpha$ -stable stochastic processes.

$$(-\Delta)^s u = 0$$

where  $u > \varphi$  (at the points of no stop)

$$(-\Delta)^s u \geq 0$$

everywhere in  $\mathbb{R}^n$

$$u \geq \varphi$$

## Properties of the fractional laplacian

The fractional Laplacian  $(-\Delta)^s$  is a nonlocal operator that has the following simple form

$$\widehat{(-\Delta)^s u}(\xi) = |\xi|^{2s} \widehat{u}(\xi)$$

It also has the following properties

- Commutes with rigid motions:  
 $(-\Delta)^s(u \circ M) = ((-\Delta)^s u) \circ M$  for any rigid motion  $M$ .
- Scales with order  $2s$  in the following sense:  
 $(-\Delta)^s u_\lambda(x) = \lambda^{2s} ((-\Delta)^s u)(\lambda x)$ , where  $u_\lambda(x) = u(\lambda x)$ .



## Regularity results

- Quasi optimal result  $u \in C^{1,\alpha}$  for every  $\alpha < s$  (CPAM 2005)
- Optimal regularity  $u \in C^{1,s}$  (Caffarelli, Salsa, S. 2007)
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## Thin Obstacle Problem - Case $s = 1/2$

$$\Delta u = 0$$

$$u(x, 0) \geq \varphi(x)$$

$$\partial_{n+1} u \leq 0$$

$$\partial_{n+1} u = 0 \text{ where } u > \varphi$$

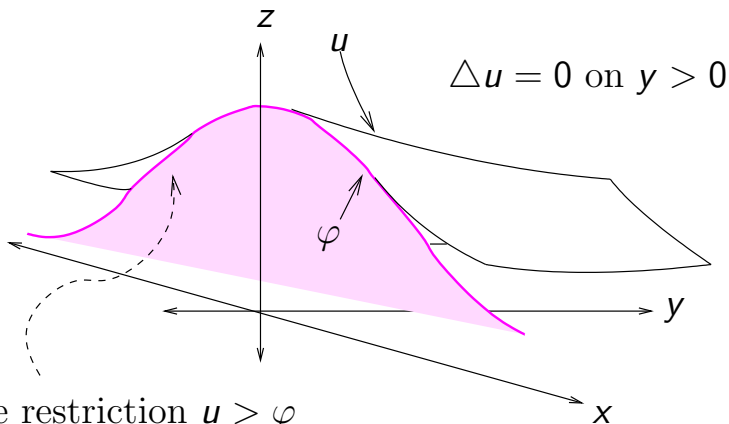
We extend the function  $u$  harmonically in the upper half space

$$\Delta u = 0 \text{ in } \{x_{n+1} > 0\},$$

then we have the relation

$$-\partial_n u(x, 0) = (-\Delta)^{1/2} u(x, 0)$$

## A drawing of the thin obstacle problem



The restriction  $u > \varphi$   
only applies where  $y = 0$

Obstacle problem for  $(-\Delta)^{1/2}$ 

The thin obstacle problem in the upper half space is equivalent to the obstacle problem on the boundary with  $L = (-\Delta)^{1/2}$ .

$$\begin{aligned}u &\geq \varphi \\(-\Delta)^{1/2}u &\geq 0 \\(-\Delta)^{1/2}u &= 0 \quad \text{where } u > \varphi\end{aligned}$$

## Regularity of the thin obstacle problem

The regularity results for the thin obstacle problem are

- $u \in C^{1,\alpha}$  for a small  $\alpha > 0$  (Caffarelli 1979)
- $u \in C^{1,1/2}$  (Athanasopoulos and Caffarelli, 2004)
- The free boundary is smooth under nondeg. assumptions (Athanasopoulos, Caffarelli and Salsa, 2006)

All these results would hold for the obstacle problem for  $(-\Delta)^{1/2}$ .

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The following properties of the Dirichlet to Neumann map can be checked directly.

Let  $u(x, y)$  be the harmonic extension to the upper half plane and let

$$Lu(x, 0) \mapsto -\partial_y u(x, 0)$$

- $L$  commutes with rigid motions:  $L(u \circ M) = (Lu) \circ M$  for any rigid motion  $M$ .
- $L$  scales with order 1 in the following sense:  
 $Lu_\lambda(x) = \lambda (Lu)(\lambda x)$ , where  $u_\lambda(x) = u(\lambda x)$ .

If we want to construct a similar extension for arbitrary fractional laplacians  $(-\Delta)^s$  we have to make it scale in a different way.

## Extension with a weight.

$$\operatorname{div}(y^a \nabla u) = 0$$

$$\curvearrowright u(x, 0) \geq \varphi(x)$$

$$\lim_{y \rightarrow 0} y^a \partial_{n+1} u \leq 0$$

$$\lim_{y \rightarrow 0} y^a \partial_{n+1} u = 0 \text{ where } u > \varphi$$

We extend the function  $u$  in the upper half space to satisfy the equation:

$$\operatorname{div}(y^a u) = 0 \text{ in } \{x_n > 0\},$$

then we have the relation

$$-\lim_{y \rightarrow 0} y^a \partial_n u(x, 0) = c(-\Delta)^{\frac{1-a}{2}} u(x, 0)$$

(Caffarelli, S., CPDE 2007)

## Equivalent local problem.

An equivalent problem to the obstacle problem for  $(-\Delta)^s$  is given by

$$\begin{aligned} \operatorname{div}(y^a \nabla u) &= 0 && \text{in } \{y > 0\}, \\ u(x, 0) &\geq \varphi(x, 0), \\ \lim_{y \rightarrow 0^+} y^a u_y(x, y) &= 0 && \text{in } \{u(x, 0) > \varphi(x, 0)\}, \\ \lim_{y \rightarrow 0^+} y^a u_y(x, y) &\leq 0 \end{aligned}$$

with  $s = (1 - a)/2$ .

## $A_2$ weights.

$|y|^a$  is degenerate near  $y = 0$  however it is in the class of  $A_2$  weights.

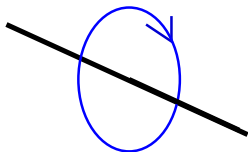
The equation  $\operatorname{div} |y|^a \nabla u = 0$  satisfies:

- Harnack inequality.
- Boundary Harnack

Fabes, Kenig, Jerison, Serapioni.

## Cylindrically symmetric harmonic functions

$$u(x, y) = \tilde{u}(x, |y|)$$



Let  $x \in \mathbb{R}^n$  and  $y \in \mathbb{R}^{1+a}$  for some number  $a$ .

Assume  $u$  is radially symmetric in  $y$ . Then we can express its Laplacian in cylindrical coordinates

$$\Delta u = \Delta_x u + \partial_{rr} u + \frac{a}{r} \partial_r u = r^{-a} \operatorname{div}(r^a \nabla u)$$

Thus the equation  $\operatorname{div}(r^a \nabla u) = 0$  basically means that  $u$  is a harmonic cylindrically symmetric function.

## Fractional dimension.

Our equivalent problem can be thought as a thin obstacle problem with fractional co-dimension  $1 + a$ .

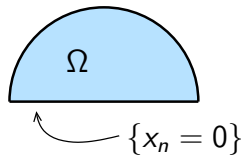
The problem can be localized.

$$\operatorname{div}(y^a \nabla u) = 0 \quad \text{in } B_1^+,$$

$$u(x, 0) \geq \varphi(x, 0) \quad \text{on } B_1 \cap \{y = 0\},$$

$$\lim_{y \rightarrow 0^+} y^a u_y(x, y) = 0 \quad \text{on } \{u(x, 0) > \varphi(x, 0)\}$$

$$\lim_{y \rightarrow 0^+} y^a u_y(x, y) \leq 0$$



with  $s = (1 - a)/2$ .

Similar methods to the ones employed to the classical thin obstacle problem will work.

## Some tools used

- Analysis of blowup sequences.
- Almgren's frequency formula

$$\Phi(r) = r \frac{\int_{B_r^+} y^a |\nabla u|^2 \, dX}{\int_{\partial B_r \cap \{y>0\}} y^a |u|^2 \, d\sigma(X)} \nearrow$$

- A Liouville theorem for blowup profiles.
- Blowup profiles at nondegenerate points have a flat free boundary  $\longrightarrow$  free boundary regularity.



## Almgren monotonicity formula

If  $u : \mathbb{R}^n \times \mathbb{R} \rightarrow \mathbb{R}$  satisfies

$$\begin{aligned}\Delta u &= 0 \text{ in } \{y > 0\} \\ u \cdot u_y &= 0 \text{ on } \{y = 0\}\end{aligned}$$

Then the following function is monotone increasing

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## Blowup sequence

Assume 0 is in the free boundary. Let

$$u_r(x) = \left( r^{-n-a} \int_{\partial B_r \cap \{y>0\}} y^a |u|^2 dX \right)^{-1/2} u(rX)$$

There is a subsequence  $u_{r_j}$  converging to a global solution to the problem  $u_0$ .

## A Liouville type theorem for blowup profiles

If  $u_0 : \mathbb{R}^n \times [0, +\infty) \rightarrow \mathbb{R}$  is a homogeneous global solution to the problem

$$\begin{aligned} \operatorname{div}(y^a \nabla u) &= 0 && \text{in } \{y > 0\}, \\ u(x, 0) &\geq 0, \\ \lim_{y \rightarrow 0^+} y^a u_y(x, y) &= 0 && \text{in } \{u(x, 0) > \varphi(x, 0)\}, \\ \lim_{y \rightarrow 0^+} y^a u_y(x, y) &\leq 0 \end{aligned}$$

with 0 in the free boundary, then either

- $u_0$  has degree  $1 + s$  and the free boundary is a plane.
- $u_0$  has degree  $\geq 2$ .

## Optimal regularity

The degree of homogeneity of  $u_0$  is the value  $\Phi(0)$  for the Almgren frequency formula.

The fact that  $\Phi(0) \geq 1 + s$  implies that  $u \in C^{1,s}$ .

## Free boundary regularity

If  $\Phi(0) = 1 + s$  then the free boundary is  $C^{1,\alpha}$  in a neighborhood of the origin.

### Idea:

The blowup limit  $u_0$  has a flat free boundary. For small  $r$ , the free boundary of  $u_r$  must be arbitrarily close to flat. Once the free boundary of  $u_r$  is almost flat, a similar proof to the one of the classical obstacle problem follows using the Boundary Harnack principle.