# $C^{1,\alpha}$ regularity for the homogeneous parabolic *p*-Laplace equation

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### Outline

#### Introduction

The *p*-Laplacian Homogeneous parabolic equations Our result

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First observations

Hölder continuity of the gradient

### The *p*-Laplace operator

Let  $p \in (0, \infty)$ . The *p*-Laplace equation arises as the Euler-Lagrange equation of the functional

$$F(u) := \int |\nabla u|^p \, \mathrm{d}x.$$

A function is *p*-Harmonic when

$$\triangle_{p} u = \operatorname{div}[|\nabla u|^{p-2} \nabla u] = 0.$$

It is a classical result that *p*-harmonic functions are  $C^{1,\alpha}$  for some  $\alpha > 0$ . The optimal value of  $\alpha$  depends on *p* and dimension and it is currently unknown in general.

Uraltseva [1968,  $p \ge 2$ ], Uhlenbeck [1977 - systems -  $p \ge 2$ ], Evans [1982,  $p \ge 2$ ], DiBenedetto [1983], Lewis [1983], Tolksdorf [1984] and Wang [1994].

## The gradient flow equation

The following parabolic *p*-Laplace equation is the gradient flow of the functional  $\int |\nabla u|^p dx$ .

$$u_t = \operatorname{div}\left[|\nabla u|^{p-2}\nabla u\right].$$

The solutions are also known to be  $C^{1,\alpha}$  in space for some  $\alpha > 0$ . This was proved by DiBenedetto and Friedman [1985] and Wiegner [1986] (some extra conditions are needed for  $p \in (1,2)$ ).

Non-divergence version of the *p*-Laplacian

Let us expand the formula of the *p*-Laplacian.

$$\Delta_{\boldsymbol{p}} \boldsymbol{u} = \operatorname{div} \left[ |\nabla \boldsymbol{u}|^{\boldsymbol{p}-2} \nabla \boldsymbol{u} \right],$$
  
=  $|\nabla \boldsymbol{u}|^{\boldsymbol{p}-2} \left( \Delta \boldsymbol{u} + (\boldsymbol{p}-2) \frac{\partial_i \boldsymbol{u} \partial_j \boldsymbol{u}}{|\nabla \boldsymbol{u}|^2} \partial_{ij} \boldsymbol{u} \right).$ 

Therefore, the elliptic equation  $\triangle_p u = 0$  is equivalent to

$$\triangle u + (p-2)\frac{\partial_i u \partial_j u}{|\nabla u|^2} \partial_{ij} u = 0.$$

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### The $\infty$ -Laplacian

The cases  $p = 1, \infty$  are special. They are best understood in non divergence form.

As  $p \to \infty$ , the equation converges to

 $\partial_i u \ \partial_j u \ \partial_{ij} u = 0.$ 

Solutions to this are  $\infty$ -Harmonic functions. They correspond to optimal Lipschitz extensions. They are known to be  $C^{1,\alpha}$  in 2D (Evans and Savin [2008]) and pointwise differentiable in arbitrary dimension (Evans and Smart [2011]). They are conjectured to be  $C^{1+1/3}$ .

The  $\infty$ -hamonic functions also correspond to the value function of the **stochastic "tug of war" game** (Peres, Schramm, Sheffield and Wilson [2009]). At the discrete level, this is a similar construction to a numerical algorithm developed by Adam Oberman [2005].

Tug of war games with a terminal time

If we impose a terminal time to the tug of war game, we derive the (homogeneous) parabolic equation

$$u_t = \frac{\partial_i u \, \partial_j u}{|\boldsymbol{\nabla} \boldsymbol{u}|^2} \, \partial_{ij} u.$$

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### Mean curvature flow

The homoegeneous parabolic equation for p = 1 reads

$$u_t = \left(\delta_{ij} - \frac{\partial_i u \partial_j u}{|\nabla u|^2}\right) \partial_{ij} u.$$

This is the evolution equation for the function *u* whose level sets follow a mean curvature flow. This equation was studied by a number of authors like Chen-Giga-Goto, Evans-Spruck, Evans-Soner-Souganidis, Ishii-Souganidis, Oberman, Minicozzi-Colding, etc...

Homogeneous parabolic *p*-Laplace equation.

Y. Peres and S. Shefield [2008] extended the tug of war game to a construction of the *p*-Laplace equation by adding lateral noise. When we add a terminal time to this game, we obtain the homogeneous parabolic equation

$$u_t = \triangle u + (p-2)\frac{\partial_i u \partial_j u}{|\nabla u|^2} \partial_{ij} u.$$

This parabolic problem was considered by Manfredi-Parviainen-Rossi [2010]. Existence and uniqueness of Lipschitz viscosity solutions was established by Does [2011] and Banerjee-Garofalo [2013].

### Our result

### Theorem (Tianling Jin, LS.)

Let *u* be a viscosity solution of the homogeneous parabolic *p*-Laplace equation

$$u_t = \triangle u + (p-2) \frac{\partial_i u \partial_j u}{|\nabla u|^2} \partial_{ij} u$$
 in  $Q_1 = (-1, 0] \times B_1$ 

then  $\nabla u$  is well defined and Hölder continuous in  $Q_{1/2} = (-1/4, 0] \times B_{1/2}.$ 

Difficulty: no variational structure. Different methods need to be used.

## Uniform ellipticity

We have the equation

$$u_t = \triangle u + (p-2) \frac{\partial_i u \partial_j u}{|\nabla u|^2} \partial_{ij} u$$
 in  $Q_1 = (-1, 0] \times B_1$ 

For

$$a_{ij} = \delta_{ij} + (p-2) \frac{\partial_i u \partial_j u}{|\nabla u|^2}.$$

Note that  $\max(p-1,1)I \ge \{a_{ij}\} \ge \min(p-1,1)I$ . The equation is uniformly elliptic in non-divergence form.

The coefficients  $a_{ij}(\nabla u)$  are a smooth function of  $\nabla u$  except where  $\nabla u = 0$ . If  $a_{ij}(\nabla u)$  was smooth everywhere resp.  $\nabla u$ , the regularity of the solution would follow from classical estimates.

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Fact 1.  $W^{2,\varepsilon}$  estimates

Solutions to uniformly parabolic equations

$$u_t = a_{ij}(x,t)\partial_{ij}u,$$

with  $\lambda I \leq \{a_{ij}\} \leq \Lambda I$ , are in  $W^{2,\varepsilon}$  for some  $\varepsilon > 0$ . This means that

$$\int_{Q_1} |D^2 u|^{\varepsilon} \, \mathrm{d} x \leq C \left( \sup_{Q_1} |u| \right)^{\varepsilon},$$

for some  $\varepsilon > 0$  and *C* universal.

Fact 2.  $|\nabla u|^p$  is a subsolution to a unif. parabolic equation

Fact 3. Local Maximum principle

Fact 1.  $W^{2,\varepsilon}$  estimates

$$\int_{Q_1} |Du|^arepsilon \, \mathrm{d} x \leq C \left( \max_{Q_1} |u| 
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Fact 1.  $W^{2,\varepsilon}$  estimates  $\int_{Q_1} |Du|^{\varepsilon} dx \leq C \left( \max_{Q_1} |u| \right)^{\varepsilon}.$ Fact 2.  $|\nabla u|^p$  is a subsolution to a unif. parabolic equation The function  $\varphi = |\nabla u|^p$  is a subsolution to  $\varphi_t - a_{ij}\partial_{ij}\varphi \leq 0.$ 

Fact 3. Local Maximum principle

### Fact 1. $W^{2,\varepsilon}$ estimates

$$\int_{Q_1} |Du|^arepsilon \, \mathrm{d} x \leq C \left( \max_{Q_1} |u| 
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### Fact 3. Local Maximum principle

Non negative subsolutions to uniformly parabolic equations in nondivergence form

$$\varphi_t - a_{ij}(x,t)\partial_{ij}\varphi \leq 0,$$

satisfy the local maximum principle

$$\varphi(0) \leq \left(\int_{Q_1} \varphi^{\varepsilon} \, \mathrm{d}x \, \mathrm{d}t\right)^{1/\varepsilon}.$$

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Fact 3. Local Maximum principle

$$\varphi(\mathbf{0}) \leq \left(\int_{Q_1} \varphi^{\varepsilon} \, \mathrm{d}x \, \mathrm{d}t\right)^{1/\varepsilon}$$

$$\Longrightarrow |\nabla u(0)| \leq C \max_{Q_1} |u|.$$

The alternative proof by Does uses Berstein's technique.

## The oscillation of $\nabla u$

#### We aim at proving that

 ${\cal C}^{\alpha}$  regularity for  $\nabla u$ 

$$\nabla u(Q_{r^k}) \subset B_{(1-\delta)^k}(p_k).$$

for some  $r, \delta \in (0, 1)$  and some sequence of centers  $p_k \in \mathbb{R}^n$  and all  $k \ge 0$ .

This is exactly the  $C^{\alpha}$  regularity of  $\nabla u$  where  $\alpha = \log(1-\delta)/\log r$ .

In order to prove it by induction, we must show (flawed) induction step

$$\nabla u(Q_1) \subset B_1 \Longrightarrow \nabla u(Q_r) \subset B_{(1-\delta)},$$

for some  $r, \delta \in (0, 1)$ .

## Improvement of oscillation

#### Lemma

Assume  $\nabla u(Q_1) \subset B_1$ . Let e be any unit vector. Assume that

$$|\{(t,x)\in Q_1:e{\cdot}
abla u(t,x)\leq 1-c_0\}|\geq \mu.$$

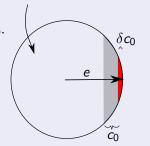
Then

$$e \cdot \nabla u(t, x) \leq 1 - \delta c_0$$
 in  $Q_r$ .

Here  $\delta$  and r are positive and depend on p and  $\mu$ .

**Proof.** The function  $w = \max(e \cdot \nabla u, 1 - c_0)$  is a subsolution of some parabolic equation.

Indeed, note that the equation is only relevant where  $1 - c_0 \le e \cdot \nabla u \le 1$ . Our equation is smooth if the gradient is restricted there. So we can differentiate the equation and obtain something.



 $\nabla u$  stays inside this ball

### The favorable case

If we can apply the previous lemma for fixed  $\mu$  and  $c_0$  and for all directions e, then we obtain that

 $\nabla u(Q_r) \subset B_{(1-\delta)},$ 

and the induction step succeeds.



 $\nabla u$  never goes into the red area.

This induction step can only work indefinitely if  $\nabla u(0) = 0$ . We cannot expect this to always happen. We must have a **backup plan** for the case when the conditions of the Lemma are not met. We can choose arbitrarily small  $\mu$  and  $c_0$ .

Small perturbation of smooth parabolic equations

### Theorem (Yu Wang [2013])

Let u be a solution to the parabolic equation

 $u_t = F(D^2u, \nabla u)$  in  $Q_1$ .

Assume F is smooth and uniformly elliptic in a neighborhood of  $(D^2\varphi, \nabla\varphi)$  for some smooth solution  $\varphi$ . If  $\|\boldsymbol{u} - \boldsymbol{\varphi}\|_{L^{\infty}}$  is sufficiently small, then  $\boldsymbol{u} \in \boldsymbol{C}^{2,\alpha}$  in  $Q_{1/2}$ .

This is the parabolic version of an earlier result by Ovidiu Savin for elliptic equations.

### The backup plan

It will eventually happen that our previous lemma does not apply. That is, for some unit vector e,

$$|\{(t,x) \in Q_1 : e \cdot \nabla u(t,x) \le 1 - c_0\}| < \mu.$$
(1)

The constants  $\mu$  and  $c_0$  are arbitrarily small.

We want to show that in this case  $u(x, t) - e \cdot x$  has a small oscillation in  $Q_{1/2}$  and we can apply the result of Yu Wang.

The condition (1) tells us that for fixed time  $u(x, t) - p \cdot x$  has small oscillation, except for a set of times of small measure.

## Small oscillation for all fixed times

The condition (1) tells us that for fixed time  $u(x, t) - p \cdot x$  has small oscillation, except for a set of times of small measure.

Recall that the function  $v(x, t) = u(x, t) - p \cdot x$  solves a uniformly parabolic equation

 $\mathbf{v}_t = \mathbf{a}_{ij} \partial_{ij} \mathbf{v},$ 

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with  $\lambda I \leq \{a_{ij}\} \leq \Lambda I$ .

Using the  $C^{\alpha}$  estimates of Krylov and Safonov, we extend the small oscillation for **all values of** *t*.

## Small oscillation for the whole parabolic cylinder

#### Lemma

Let v be a solution to the uniformly parabolic equation  $v_t = a_{ij}\partial_{ij}v$ . Assume that

$$\mathop{\mathrm{osc}}_{x\in B_1} v(t,x) \leq \delta$$
 for all  $t\in [-1,0].$ 

Then,

$$\operatorname{osc}_{Q_1} v(t,x) \leq C\delta,$$

for a constant C depending on dimension and the ellipticity constants.

Proof. Use barriers of the form

$$w(t,x) = a + \delta |x|^2 + C\delta t.$$

This is a supersolution for large enough C.

## Summary of strategy

For as long as we can apply the first lemma, we get

 $\nabla u(B_{r^k}) \subset B_{(1-\delta)^k}.$ 

Whenever the first lemma fails, that means there is a unit vector e so that  $\nabla u$  is very close to e at most points in  $Q_1$ .

Using the uniform ellipticity of the equation (in non-divergence form) we deduce that  $u(t, x) - p \cdot x$  has a small oscillation and we conclude applying the result of Yu Wang.

Both alternative co-exist peacefully and we obtain a uniform  $C^{\alpha}$  estimate for  $\nabla u$  in  $Q_{1/2}$ .