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Dear Masha,

I agree with you that the issue of hypergeometric kappas with complex alphas and betas is not particularly important and can be left as a remark. Having said that, I do want to check for myself that the assertion is true. For this we need to look at deformation of parameters. This is a bit confusing because we want to fix the singular points (poles), but we want the local exponents to move. Let  $R$  be a  $\mathbb{C}$ -algebra (commutative) and fix  $x_0 \in \text{Spec}(R)$  a closed  $\mathbb{C}$ -point. Let  $L_R = L = \sum q_{n-i}(t)D^i = \sum t^j p_j(D) \in \mathcal{D} \otimes_{\mathbb{C}} R$  be a differential operator with coefficients in  $R$  and we consider the family of differential operators  $L_x$  as  $x$  runs through the closed points of  $\text{Spec}(R)$ . We assume  $q_0(t) \in \mathbb{C}[t, t^{-1}]$  is independent of  $R$  which has as effect that varying the closed point  $x$  does not vary the poles of  $L_x$ .

**Example 1.** [*Hypergeometric family*] Consider the case of hypergeometrics of degree  $(n, n)$ . In this case

$$L = \prod_{i=1}^n (D - \alpha_i^0) - t \prod_{j=1}^n (D - \beta_j^0) = (1-t)D^n - \sum_{i=1}^n (\alpha_i^0 - t\beta_i^0)D^{n-1} + \dots$$

If we replace constants  $\alpha_i^0$  and  $\beta_j^0$  with variable  $\alpha_i, \beta_j \in R$  we obtain a family  $L_R = \prod (D - \alpha_i) - t \prod (D - \beta_j) = (1-t)D^n + \dots$ . Note that the pole set  $\{0, 1, \infty\}$  does not move.

We next consider local exponents. Let  $I(s) = p_0(s)$ . Define

$$\mathcal{R} := R[s][I(s+n)^{-1}, n > 0 \in \mathbb{N}]/(I(s))$$

By definition, a *local exponent* is a  $\mathbb{C}$ -point  $\ell : \mathcal{R} \rightarrow \mathbb{C}$ . The arguments at the beginning of section 3 of the paper then imply that the formal generating series  $\Phi_{\mathcal{R}}(s, t) = \sum_{n=0}^{\infty} a_n(s)t^{n+s}$  satisfying  $L\Phi_{\mathcal{R}} = 0$  is defined. for a local exponent  $\ell : \mathcal{R} \rightarrow \mathbb{C}$  we can define a differential operator  $L_{\ell}$  over  $\mathbb{C}$  (defined by the composition  $l : R \rightarrow \mathcal{R} \xrightarrow{\ell} \mathbb{C}$ ) and a generating series of solutions and inhomogeneous solutions  $\Phi_{\ell}(s, t) = \sum \ell(a_n(s))t^{n+\ell(s)}$ . In this sense,  $\text{Spec}(\mathcal{R})$  parametrizes deformations of solutions.

One usually wants the parameter space  $\text{Spec}(\mathcal{R})$  to be smooth, say at a point  $\ell$ .

**Proposition 2.** *Assuming  $R$  is smooth at the point defined by  $l : R \rightarrow \mathcal{R} \xrightarrow{\ell} \mathbb{C}$ , a sufficient condition for  $\mathcal{R}$  to be smooth at  $\ell$  is that the local exponent at the  $\mathbb{C}$ -point  $\ell$  has multiplicity 1.*

*Proof.* We have  $\text{Spec}(\mathbb{R}[s][I(s+n)^{-1}, n > 0 \in \mathbb{N}] \rightarrow \text{Spec}(R)$  with fibre the affine line with parameter  $s$ . The locus  $I(s) = 0$  meets the fibre in the local exponents at  $\ell$ . If all local multiplicities are one, this intersection is smooth, so by standard algebraic geometry  $\mathcal{R}$  is smooth at  $\ell$ .  $\square$

**Example 3** (hypergeometric family (cont.)). *Take  $\alpha_i, \beta_j \in R$  and let  $L_R = \prod(D - \alpha_i) - t \prod(D - \beta_j)$ . Let  $\alpha_i^0, \beta_j^0$  as in example 1 above arise by specializing using a  $\mathbb{C}$ -point  $l : R \rightarrow \mathbb{C}$ . Since  $L$  is assumed to be a hypergeometric,  $l$  will lift to a  $\mathbb{C}$ -point  $\ell : \mathcal{R} \rightarrow \mathbb{C}$ . At  $t = 0$ , the local exponents are defined by  $\prod_1^n (s - \alpha_i)$ . If the  $\alpha_i^0$  are distinct, it follows that  $\mathcal{R}$  is smooth at  $\ell$ .*

At this point it is convenient to change viewpoints. Rather than thinking of differential operators  $L$  with coordinates in a ring  $R$ , we think of  $R \subset \mathcal{O}(\Delta)$  as a subring of the ring of analytic functions on a disk. We get in this way a family of differential operators parametrized by points  $x \in \Delta$ . Let  $\{p_1, \dots, p_n\} \subset \mathbb{P}^1$  be the polar locus. What this construction gives is a family of connections on  $\mathbb{P}^1 - \{p_1, \dots, p_n\}$  parametrized by  $\Delta$ , i.e. a vector bundle  $\mathcal{V}$  on  $c) \times \Delta$  with a connection relative to  $\Delta$ .

Fix a basepoint  $b \in \mathbb{P}^1 - \{p_1, \dots, p_n\}$ . Let  $\sigma$  be a loop around  $p_n$  based at  $b$ . For a point  $x \in \Delta$ , we consider the monodromy along  $\sigma$  in  $\mathcal{V}|_{(\mathbb{P}^1 - \{p_1, \dots, p_n\})_x}$ .  $\sigma$  acts fibrewise:  $\sigma_* : \mathcal{V}_b \times \Delta \rightarrow \mathcal{V}_b \times \Delta$ .

Take  $p_1 = 0 \in \mathbb{P}^1$  and Let  $\mathcal{R}$  be the  $R$ -algebra of local exponents at  $p_1$ . Let  $\ell : \mathcal{R} \rightarrow \mathbb{C}$  be a smooth point. Take a disk  $\Delta \rightarrow \text{Spec}(R)$  as above in such a way that  $\ell$  lies over the center of  $\Delta$ . Let  $\Phi_{\mathcal{R}}(s, t)$  be the generating series of solutions and inhomogeneous solutions parametrized by  $\mathcal{R}$  as above. Fix a path  $\mu$  from  $p_1$  to  $b$ , and transport  $\Phi_R$  along  $\mu$  to  $b$ . Restricting to  $\Delta$  and localizing analytically on  $\Delta$ , we can suppose we have smooth families of sections  $\phi_{i,\Delta}$ ,  $i = 0, 1, 2, \dots$  on  $\mathcal{V}_{b \times \Delta}$ . We assume (after localizing)  $\phi_{0,\Delta}$  does not vanish at any point on  $\Delta$ . (More precisely, we assume  $\phi_{0,\ell}$  doesn't vanish and then we shrink  $\Delta$  if necessary.)

Assume  $\sigma_* - Id : \mathcal{V}_b \rightarrow \mathcal{V}_b$  has everywhere rank  $\leq 1$ , and that  $(\sigma_* - Id)(\phi_0)|_{0 \in \Delta} \neq 0$ . Shrinking  $\Delta$ , we can assume  $(\sigma_* - Id)(\phi_0)$  is nowhere zero so  $(\sigma_* - Id)$  has everywhere rank 1, and  $\mathcal{L}$  over  $\Delta$  defined by  $\mathcal{L} := \text{Image}(\sigma_* - Id) \subset \mathcal{V}_b$  is a line bundle. Identify  $\mathcal{L} = \mathbb{C}_{\Delta}$  by sending  $(\sigma_* - Id)(\phi_0) \mapsto 1 \times \Delta$ .

**Definition 4.** *With notation as above, for  $n < N$  we define  $\kappa_n = (\sigma_* - Id)(\phi_n)$ . This is a section of  $\mathcal{L} = \mathbb{C}_\Delta$ , i.e. a (possibly non-constant) analytic function on  $\Delta$ .*

**Corollary 5.** *With assumptions as above,  $\kappa_n$  is an analytic function on  $\Delta$ . In particular, it can be expanded in a Taylor series about  $0 \in \Delta$ .*

**Corollary 6.** *In the hypergeometric case (example 1), the formula*

$$(1) \quad \frac{1}{A(s)} = \sum_{n \geq 0} \kappa_{\rho,n} (s - \rho)^n$$

*which is proven in the paper (Example 23) for the case when  $\alpha$ 's and  $\beta$ 's are real, is true for any complex  $\alpha$ 's and  $\beta$ 's, assuming no two coordinates differ by an integer.*

*Proof.* Start with  $\alpha_j^0, \beta_k^0 \in \mathbb{R}$ . We consider the Taylor series coefficients. At the  $\mathbb{R}$ -point with coordinates  $(\alpha^0, \beta^0)$  we have

$$\frac{\partial^n}{\partial s^n} \frac{1}{A(s)} = n! \kappa_{\rho,n}(s)$$

We have seen that the  $\kappa_n$  are analytic in a neighborhood, so we can now compute the Taylor series for both sides in the  $\mathbb{R}$ -variables  $\alpha^0, \beta^0$ , and these  $\mathbb{R}$ -Taylor series will coincide. It follows that the formula (6) is valid in a  $\mathbb{C}$ -open set since both sides have convergent Taylor series. By analytic extension, the formula is valid on the open domain where the functions are defined.  $\square$