

## Solutions to HW #1

## Exercise 1.

- i. Following the notes, we can assume the solution is unique and thus given by the integral discussed in class. Hence for any fixed  $(x, t)$ :

$$\begin{aligned}
 u(x, t) &= \int_{\mathbb{R}} \Phi(x - y, t) g(y) dy \\
 &= \int_{\mathbb{R}} \Phi(y, t) g(x - y) dy \\
 &< \int_{\mathbb{R}} \Phi(y, t) \|g\|_{\infty} dy \\
 &= \|g\|_{\infty} \int_{\mathbb{R}} \Phi(y, t) dy \\
 &= \|g\|_{\infty}
 \end{aligned}$$

where the inequality follows from the fact that if  $f: \mathbb{R} \rightarrow \mathbb{R}^+$  is a continuous, non-constant function, then  $\int_{\mathbb{R}} f(y) dy > 0$ . [Can you see that? Since it is not constant, there must exist an  $a > 0$  such that  $f(x) = a$  for some  $x \in \mathbb{R}$ . Then, by continuity, there is a  $\delta > 0$  such that  $f(y) \geq a/2$  for  $y \in [x - \delta, x + \delta]$  and so  $\int_{\mathbb{R}} f(y) dy \geq \delta a > 0$ .] We took  $f(y) = \Phi(y, t) \{\|g\|_{\infty} - g(x - y)\} \geq 0$  here.

- ii. Similarly:

$$\begin{aligned}
 \|u(t)\|_2^2 &= \int_{\mathbb{R}} u(x, t)^2 dx = \int_{\mathbb{R}} \left\{ \int_{\mathbb{R}} \Phi(y, t) g(x - y) dy \right\}^2 dx \\
 &= \int_{\mathbb{R}} \left\{ \int_{\mathbb{R}} \Phi(y_1, t) g(x - y_1) dy_1 \right\} \left\{ \int_{\mathbb{R}} \Phi(y_2, t) g(x - y_2) dy_2 \right\} dx \\
 &= \int_{\mathbb{R}} \Phi(y_1, t) \Phi(y_2, t) \int_{\mathbb{R}} g(x - y_1) g(x - y_2) dx dy_1 dy_2 \\
 &< \int_{\mathbb{R}} \Phi(y_1, t) \Phi(y_2, t) \|g\|_2^2 dy_1 dy_2 \\
 &= \|g\|_2^2
 \end{aligned}$$

where the inequality follows from an argument similar to that in (i), since by the Cauchy-Schwarz inequality

$$f(y_1, y_2) = \int g(x - y_1) g(x - y_2) dx - \int g(x)^2 dx \leq 0$$

and moreover  $f$  is non-constant and clearly continuous,

iii. Here

$$\begin{aligned}
 \|u(t)\|_1 &= \int_{\mathbb{R}} |u(x, t)| dx = \int_{\mathbb{R}} \left| \int_{\mathbb{R}} \Phi(y, t) g(x - y) dy \right| dx \\
 &< \int_{\mathbb{R}} \int_{\mathbb{R}} \Phi(y, t) |g(x - y)| dy dx \\
 &= \int_{\mathbb{R}} \Phi(y, t) dy \|g\|_1 \\
 &= \|g\|_1
 \end{aligned}$$

where the inequality follows from that fact that  $|\int f(x) dx| < \int |f(x)| dx$  for any  $f$  that changes sign.

**Exercise 2.** All four sub-problems below require the same approach, namely first expressing derivatives of  $v$  in terms of derivatives of  $u$  and then eliminating the latter using the PDE that  $u$  satisfies.

i. Observe that  $v_s(y, s) = \delta u_t(\gamma y, \delta s)$  and  $v_{yy}(y, s) = \gamma^2 u_{xx}(\gamma y, \delta s)$ , hence

$$v_t = \frac{\delta}{\gamma^2} v_{xx}$$

and this equation is the same as that for  $u$  if and only if  $\delta = \gamma^2$ .

ii. Here  $v_t(x, t) = e^{\alpha x} u_t(x, t)$ ,  $v_x(x, t) = \alpha v(x, t) + e^{\alpha x} u_x(x, t)$ , and differentiating again

$$v_{xx}(x, t) = \alpha^2 v(x, t) + 2\alpha e^{\alpha x} u_x(x, t) + e^{\alpha x} u_{xx}(x, t).$$

Hence  $e^{\alpha x} u_x(x, t) = v_x(x, t) - \alpha v(x, t)$  and putting all of this together gives

$$v_t(x, t) = e^{\alpha x} u_t(x, t) = e^{\alpha x} u_{xx}(x, t) = v_{xx}(x, t) - \alpha^2 v(x, t) - 2\alpha [v_x(x, t) - \alpha v(x, t)],$$

finally yielding

$$v_t = v_{xx} - 2\alpha v_x + \alpha^2 v.$$

iii. Here  $v_t(x, t) = \beta v(x, t) + e^{\beta t} u_t(x, t)$  and  $v_{xx}(x, t) = e^{\beta t} u_{xx}(x, t)$ , so

$$v_t = v_{xx} + \beta v.$$

iv. We begin by simplifying the PDE

$$v_t = \sigma v_{xx} + \lambda v_x + c v.$$

Our idea is to somehow reverse the transformations above, i.e. to use (ii) to get rid of  $v_x$ , then (iii) to eliminate  $v$ , and finally (i) to remove the constant, thus reducing this PDE to the heat equation.

First, we set  $u^{(1)}(x, t) = e^{-\alpha x} v(x, t)$  for some constant  $\alpha$  to be specified soon. Then

$$\begin{aligned}
 u_t^{(1)}(x, t) &= e^{-\alpha x} v_t(x, t) = e^{-\alpha x} \{ \sigma v_{xx} + \lambda v_x + c v \} \\
 &= e^{-\alpha x} \left\{ \sigma [\alpha^2 v(x, t) + 2\alpha e^{\alpha x} u_x^{(1)}(x, t) + e^{\alpha x} u_{xx}^{(1)}(x, t)] \right. \\
 &\quad \left. + \lambda [\alpha v(x, t) + e^{\alpha x} u_x^{(1)}(x, t)] + c v(x, t) \right\}
 \end{aligned}$$

and we see that if  $2\sigma\alpha = -\lambda$ , then the first derivative disappears and we are left with

$$u_t^{(1)}(x, t) = \sigma u_{xx}^{(1)}(x, t) + (\sigma\alpha^2 + \lambda\alpha + c) u^{(1)}(x, t),$$

where  $\alpha = -\frac{\lambda}{2\sigma}$ .

Second, we let  $u^{(2)}(x, t) = e^{-\beta t} u^{(1)}(x, t)$ , again for some constant  $\beta$ , and obtain

$$u_t^{(2)}(x, t) = e^{-\beta t} \left[ u_t^{(1)}(x, t) - \beta u(x, t) \right] = e^{-\beta t} \left\{ \sigma u_{xx}^{(1)}(x, t) + (\sigma \alpha^2 + \lambda \alpha + c - \beta) u^{(1)}(x, t) \right\}.$$

For  $\beta = \sigma \alpha^2 + \lambda \alpha + c = \sigma \frac{\lambda^2}{4\sigma^2} - \frac{\lambda^2}{2\sigma} + c = c - \frac{\lambda^2}{4\sigma}$  the above simplifies to

$$u_t^{(2)}(x, t) = \sigma u_{xx}^{(2)}(x, t).$$

Finally, we let  $u(x, t) = u^{(2)}(x, \delta t)$ . Thus  $u_t(x, t) = \delta \sigma u_{xx}(x, t)$  and setting  $\delta = \sigma^{-1}$  we recover the heat equation

$$u_t = u_{xx}.$$

Working back to express  $u$  in terms of the original  $v$  gives

$$u(x, t) = e^{-\beta t/\sigma - \alpha x} v(x, t/\sigma)$$

and more interestingly

$$v(x, t) = e^{\beta t + \alpha x} u(x, \sigma t) = \exp \left\{ \left( c - \frac{\lambda^2}{4\sigma} \right) t - \frac{\lambda}{2\sigma} x \right\} u(x, \sigma t).$$

Now, the last step in determining  $v$  is to find  $u$ , which will have to satisfy

$$\begin{cases} u_t = u_{xx} & x \in \mathbb{R}, t > 0 \\ u(x, 0) = e^{-\alpha x} v(x, 0) = e^{-\alpha x} g(x) \end{cases}$$

Fortunately, the solution to this is given in the notes as

$$u(x, t) = \int_{\mathbb{R}} \Phi(x - y, t) e^{-\alpha y} g(y) dy,$$

leading us to conclude that

$$v(x, t) = \exp \left\{ \left( c - \frac{\lambda^2}{4\sigma} \right) t - \frac{\lambda}{2\sigma} x \right\} \int_{\mathbb{R}} \Phi(x - y, \sigma t) e^{\lambda y/(2\sigma)} g(y) dy.$$

**Exercise 3.** The idea here is almost the same as in the previous exercise.

i. Since  $u = e^v$ , differentiating gives

$$\begin{aligned} u_t &= e^v v_t \\ u_x &= e^v v_x \\ u_{xx} &= e^v (v_x)^2 + e^v v_{xx} \end{aligned}$$

Combining these with the heat equation for  $u$  and cancelling the exponentials gives  $v_t = v_{xx} + (v_x)^2$  and the initial condition becomes  $v(x, 0) = \log(g(x, 0))$ .

ii. Differentiating gives

$$\begin{aligned} u_t(x, t) &= v_t(e^{\lambda x}, t) \\ u_x(x, t) &= \lambda e^{\lambda x} v_x(e^{\lambda x}, t) \\ u_{xx}(x, t) &= \lambda^2 e^{\lambda x} v_x(e^{\lambda x}, t) + (\lambda e^{\lambda x})^2 v_{xx}(e^{\lambda x}, t). \end{aligned}$$

Combining these and substituting  $y = e^{\lambda x}$  gives  $v_t(y, t) = \lambda^2 y v_y(y, t) + (\lambda y)^2 v_{yy}(y, t)$ . The domain  $\mathbb{R} \times \mathbb{R}^+$  is mapped onto  $\mathbb{R}^+ \times \mathbb{R}^+$  and thus  $v$  satisfies the following initial value problem:

$$\begin{cases} v_t = (\lambda y)^2 v_{yy} + \lambda^2 y v_y & y > 0, t > 0 \\ v(y, 0) = g\left(\frac{\log y}{\lambda}, 0\right) & y > 0 \end{cases}$$

**Exercise 4.** Observe that, by **Exercise 2(iii)** we have  $u(x, t) = e^{-2t} v(x, t)$  where  $v$  satisfies

$$\begin{cases} v_t = v_{xx} & x \in (0, \pi), t \in (0, T] \\ v(x, 0) = \sin(x) + 3 & x \in [0, \pi] \\ v(0, t) = 3e^{2t} = v(\pi, t) & t \in [0, T] \end{cases}$$

Notice that  $v$  satisfies the maximum principle (as stated in the notes), so in particular it achieves its minimum on the boundary. Since  $v$  is always positive on the boundary (i.e.  $v(x, 0) > 0$  and  $v(0, t) = v(\pi, t) > 0$ ), it follows that  $v(x, t) > 0$  for all  $x \in (0, \pi), t \in (0, T]$  and the same holds true for  $u$ , being a positive multiple of  $v$ . Thus we cannot have  $u(x, t) = 0$  in the domain.

**Exercise 5.**

a) Define  $v := u - 1$  which thus satisfies

$$\begin{cases} v_t = v_{xx} & x > 0, t > 0 \\ v(x, 0) = -1 & x > 0 \\ v(0, t) = 0 & t > 0 \end{cases}$$

Thus using the integral representation from the notes for  $v$  we can represent it as

$$u(x, t) = 1 - \frac{1}{\sqrt{4\pi t}} \int_0^\infty \left( e^{-\frac{|x-y|^2}{4t}} - e^{-\frac{|x+y|^2}{4t}} \right) dy \quad (1)$$

b) Although it is not clear how to evaluate the above integral, we can still recognize that

$$u(x, t) = 1 - \mathbb{P}\left(X > -\frac{x}{\sqrt{2t}}\right) + \mathbb{P}\left(X > \frac{x}{\sqrt{2t}}\right) = \mathbb{P}\left(|X| > \frac{x}{\sqrt{2t}}\right)$$

for a random variable  $X \sim N(0, 1)$ . [Can you see this? Work out ALL the details, so that you are completely comfortable switching between the heat kernel and the probabilistic interpretations.]

From this representation we easily show that

$$|u(x, t) - 1| = \mathbb{P}\left(|X| < \frac{x}{\sqrt{2t}}\right) = 2 \int_0^{x/\sqrt{2t}} \frac{e^{-y^2/2}}{\sqrt{2\pi}} dy \leq 2 \frac{x}{\sqrt{2t}} \frac{1}{\sqrt{2\pi}} = \frac{C(x)}{\sqrt{t}}$$

as required.

It is instructive, however, to see how you can also deduce this straight from the original expression. Observe that rearranging (1) we get

$$\begin{aligned} 1 - u(x, t) &= \frac{1}{\sqrt{4\pi t}} \int_0^\infty \left( e^{-\frac{|x-y|^2}{4t}} - e^{-\frac{|x+y|^2}{4t}} \right) dy \\ &= \frac{1}{\sqrt{4\pi t}} \left\{ \int_0^\infty e^{-\frac{|x-y|^2}{4t}} dy - \int_{-\infty}^0 e^{-\frac{|x-y|^2}{4t}} dy \right\} \\ &= \int_{\mathbb{R}} \Phi(x-y, t) g(y) dy \end{aligned}$$

where  $g(y) = 1$  for  $y \geq 0$  and  $g(y) = -1$  for  $y < 0$ . Since the function  $y \mapsto \Phi(x-y, t)$  is symmetric about  $y = x \geq 0$ , we have

$$\int_{-\infty}^0 \Phi(x-y, t) g(y) dy = - \int_{-\infty}^0 \Phi(x-y, t) dy = - \int_{2x}^\infty \Phi(x-y, t) dy = - \int_{2x}^\infty \Phi(x-y, t) g(y) dy$$

and so

$$|u(x, t) - 1| = \int_0^{2x} \Phi(x-y, t) g(y) dy \leq \frac{2x}{\sqrt{4\pi t}} = \frac{C(x)}{\sqrt{t}}$$

as before.

**Exercise 6.**

i. Clearly

$$|\hat{f}(\xi)| = \left| \int e^{-2\pi i x \cdot \xi} f(x) dx \right| \leq \int |e^{-2\pi i x \cdot \xi}| |f(x)| dx = \int |f(x)| dx = \|f\|_1$$

ii. Looking at the  $j$ th component and integrating by parts gives

$$\begin{aligned} [\widehat{\nabla f}(\xi)]_j &= \int e^{-2\pi i x \cdot \xi} \partial_{x_j} f(x) dx = e^{-2\pi i x \cdot \xi} f(x) \Big|_{x=-\infty}^{x=+\infty} - \int (-2\pi i \xi_j) e^{-2\pi i x \cdot \xi} f(x) dx \\ &= 2\pi i \xi_j \int e^{-2\pi i x \cdot \xi} f(x) dx = 2\pi i \xi_j \hat{f}(\xi) \end{aligned}$$

where we use the fact that  $f(x) \rightarrow 0$  as  $|x| \rightarrow \infty$ . Hence

$$\int |\nabla f(x)|^2 dx = \int |\widehat{\nabla f}(\xi)|^2 d\xi = \int |2\pi \xi \hat{f}(\xi)|^2 d\xi$$

as desired, where the first equality is an application of the Plancherel identity.

iii. Here

$$\begin{aligned} \int |f(x)|^2 dx &= \int |\hat{f}(\xi)|^2 d\xi = \int_{|\xi| < R} |\hat{f}(\xi)|^2 d\xi + \int_{|\xi| \geq R} |\hat{f}(\xi)|^2 d\xi \\ &\leq \int_{|\xi| < R} \|f\|_1^2 d\xi + \int \frac{|2\pi \xi|^2}{|2\pi R|^2} |\hat{f}(\xi)|^2 d\xi \\ &= C_n R^n \|f\|_1^2 + \frac{1}{(2\pi R)^2} \int |\nabla f(x)|^2 dx \end{aligned}$$

where we used the fact that from (i)  $\sup_{\xi} |\hat{f}(\xi)| \leq \|f\|_1$ .

iv. It follows that

$$\int |\nabla f(x)|^2 dx \geq (2\pi)^2 \left\{ \|f\|_2^2 R^2 - C_n \|f\|_1^2 R^{n+2} \right\},$$

so equating the derivative of the RHS to zero gives

$$2 \|f\|_2^2 \bar{R} - (n+2) C_n \|f\|_1^2 \bar{R}^{n+1} = 0$$

and so

$$\bar{R}^n = \frac{2 \|f\|_2^2}{(n+2) C_n \|f\|_1^2}.$$

Evaluating the inequality at this particular  $R$  yields

$$\begin{aligned} \int |\nabla f(x)|^2 dx &\geq (2\pi)^2 \left\{ \|f\|_2^2 - C_n \|f\|_1^2 \frac{2 \|f\|_2^2}{(n+2) C_n \|f\|_1^2} \right\} \left( \frac{2 \|f\|_2^2}{(n+2) C_n \|f\|_1^2} \right)^{2/n} \\ &= D_n \|f\|_2^2 \left( \frac{\|f\|_2^2}{\|f\|_1^2} \right)^{2/n} \\ &= D_n \|f\|_2^{2(1+2/n)} \|f\|_1^{-4/n} \end{aligned}$$

as desired.

**Exercise 7.**

- i. Interchanging the derivative and the integral

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \int |u|^2 dx &= \int u \partial_t u dx = \int u \nabla \cdot (a(x) \nabla u) dx \\ &= \int \nabla \cdot (u a(x) \nabla u) dx - \int \nabla u \cdot (a(x) \nabla u) dx \\ &= - \int a(x) |\nabla u|^2 dx \end{aligned}$$

where the last step follows by Divergence Theorem, since both  $u$  and  $\nabla u$  vanish at infinity sufficiently fast.

- ii. Notice that by the Divergence Theorem again

$$\frac{d}{dt} \int u(x, t) dx = \int \partial_t u(x, t) dx = \int \nabla \cdot (a(x) \nabla u) dx = 0,$$

hence  $\int u(x, t) dx$  cannot depend on  $t$ .

- iii. Applying the result from **Exercise 6(iv)** to  $u$  and using the fact that from (ii) we must have  $\|u(t)\|_1 \geq |\int u(x, t) dx| = |\int u_0(x) dx| = \|u_0\|_1$  (since  $u_0 \geq 0$ ) for all  $t$  yields

$$\int |\nabla u|^2 dx \geq D_n \|u\|_2^{2(1+2/n)} \|u_0\|_1^{-4/n}.$$

Hence since  $1 < a(x) < 2$  we have

$$\frac{1}{2} \frac{d}{dt} \|u\|_2^2 \leq - \int |\nabla u|^2 dx \leq - D_n \|u\|_2^{2(1+2/n)} \|u_0\|_1^{-4/n}$$

and so

$$\|u\|_2^{2(-1-2/n)} \frac{d}{dt} \|u\|_2^2 \leq - 2 D_n \|u_0\|_1^{-4/n}$$

and integrating with respect to  $t$  gives

$$-\frac{n}{2} \left\{ \|u(t)\|_2^{2(-2/n)} - \|u_0\|_2^{2(-2/n)} \right\} \leq - 2 D_n \|u_0\|_1^{-4/n} t$$

so that

$$\|u(t)\|_2^{2(-2/n)} \geq \frac{4}{n} D_n \|u_0\|_1^{-4/n} t + \|u_0\|_2^{2(-2/n)} \geq \frac{4}{n} D_n \|u_0\|_1^{-4/n} t$$

and

$$\|u(t)\|_2^2 \leq \frac{B_n}{t^{n/2}} \|u_0\|_1^2,$$

which after taking square root becomes

$$\|u(t)\|_2 \leq \sqrt{\frac{B_n}{t^{n/2}}} \|u_0\|_1.$$

- iv. Consider the linear operator  $S(t): L_1 \rightarrow L_2$  given by  $u_0 \mapsto u(t)$ . The last inequality of part (iii) shows that this is a bounded operator between the two spaces, so its adjoint  $S(t)^*: L_2 \rightarrow L_\infty$  is a bounded operator as well with the same norm. Now the adjoint satisfies

$$\int u_0 S(t)^* [\varphi] dx = \int S(t)[u_0] \varphi dx = \int u(t) \varphi dx$$

where  $\varphi \in L^2$ . Since  $u_0 \in C_c^\infty(\mathbb{R}^n)$ , we can take  $\varphi = u_0$  from which follows that in fact  $S(t)^*[u_0] = u(t)$ , so that  $S(t)^*$  is the same operator as  $S(t)$ , which is thus bounded as an operator from  $L_2$  to  $L_\infty$ . Finally

$$S(t)[u_0] = S(t/2)[S(t/2)[u_0]]$$

so that

$$\begin{aligned} \|S(t)\|_{L_1 \rightarrow L_\infty} &\leq \|S(t/2)\|_{L_1 \rightarrow L_2} \|S(t/2)\|_{L_2 \rightarrow L_\infty} \\ &\leq \sqrt{\frac{B_n}{(t/2)^{n/2}}} \sqrt{\frac{B_n}{(t/2)^{n/2}}} \\ &= \frac{B'_n}{t^{n/2}}. \end{aligned}$$